

Amendments to the Claims:

The listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

Claims 1-10 (Canceled)

Claim 11 (Currently Amended): A control system for a motor vehicle, comprising a manual actuator with a plurality of degrees of freedom of adjustment for at least one of selecting and activating entries in a menu structure with a plurality of menu levels, and a screen display having a plurality of display areas for displaying the menu structure, each of the display areas comprising at least one field for displaying one of the entries, wherein, in an active display area in at least one level of the menu structure, at least two entries are simultaneously assigned to a settable parameter for setting with the manual actuator, a first entry being an analog display of the settable parameter, and second entry being a digital display of the settable parameter.

Claim 12 (Previously Presented): The control system as claimed in claim 11, wherein the at least one parameter can be set by adjustment movement with at least one of a first, second, third or fourth of the plurality of degrees of freedom of adjustment of the manual actuator.

Claim 13 (Previously Presented): The control system as claimed in claim 12, wherein the setting performed by operating the actuator with a fifth degree of freedom of adjustment is stored, and the active display area is exited and closed.

Claim 14 (Previously Presented): The control system as claimed in claim 12, wherein at least one of the degrees of freedom of adjustment of the manual actuator corresponds to orientation of the parameter which is displayed in one of the entries.

Claim 15 (Previously Presented): The control system as claimed in claim 14, wherein the setting performed by operating the actuator with a fifth degree of freedom of adjustment is stored, and the active display area is exited and closed.

wherein the setting performed by operating the actuator with a fifth degree of freedom of adjustment is stored, and the active display area is exited and closed.

Claim 16 (Previously Presented): The control system as claimed in claim 12, wherein the settable parameter comprises a plurality of settable

subparameters, one of which can be selected in each case by actuating the manual actuator with a sixth or seventh degree of freedom of adjustment.

Claim 17 (Previously Presented): The control system as claimed in claim 16, wherein the setting performed by operating the actuator with a fifth degree of freedom of adjustment is stored, and the active display area is exited and closed.

Claim 18 (Previously Presented): The control system as claimed in claim 17, wherein at least one of the degrees of freedom of adjustment of the manual actuator corresponds to orientation of the parameter which is displayed in one of the entries.

Claim 19 (Previously Presented): The control system as claimed in claim 16, wherein the subparameter which is selected for the purpose of setting is visually highlighted by a changed graphic display.

Claim 20 (Currently Amended): The control system as claimed in claim 11, wherein ~~the at least one~~ settable parameter represents a time.

Claim 21 (Previously Presented): The control system as claimed in claim 20, wherein a first subparameter represents hours, a second subparameter represents minutes and a third subparameter represents seconds.

Claim 22 (Previously Presented): The control system as claimed in claim 12, wherein, in an x-y-z coordinate system, the first degree of freedom of adjustment is pushing of the manual actuator in a positive y direction, the second degree of freedom of adjustment is pushing of the manual actuator in a negative y direction, the third degree of freedom of adjustment is rotation of the manual actuator in a clockwise direction about a z axis, the fourth degree of freedom of adjustment is rotation of the manual actuator in a counter-clockwise direction about a z axis, and a fifth degree of freedom of adjustment is pressing of the manual actuator in a negative z direction.

Claim 23 (Previously Presented): The control system as claimed in claim 12, wherein, in an x-y-z coordinate system, a sixth degree of freedom of adjustment is pushing of the manual actuator in a positive x direction, and a seventh degree of freedom of adjustment is pushing of the manual actuator in a negative x direction.